Math 22

Fall 2018

Midterm 2

October 23, 2018

NAME:		
SECTION (check one box):	Section 1 (S. Allen 12:50) Section 2 (A. Babei 2:10)	

Instructions:

- 1. Write your name legibly on this page, and indicate your section by checking the appropriate box.
- 2. Except on clearly indicated short answer problems, you must explain what you are doing, and show your work. You will be *graded on your work*, not just on your answer. Make it clear and legible so we can follow it.
- 3. It is fine to leave your answer in a form such as $\sqrt{239}$ or $(385)(13^3)$. However, if an expression can be easily simplified (such as $\cos(\pi)$ or (3-2)), you should simplify it.
- 4. You may use the last 2 pages and the back of each page for scrap paper. Unless you run out of space and clearly indicate that your solutions are on any designated space for scrap paper, *scrap paper will not be graded*.
- 5. This exam is closed book. You may not use notes, computing devices (calculators, computers, cell phones, etc.) or any other external resource. It is a violation of the honor code to give or receive help on this exam.

Problem	Points	Score
1	7	
2	12	
3	3	
4	12	
5	9	
6	10	
7	5	
Total	58	

- 1. [7 points] Please indicate whether the following statements are TRUE (T) or FALSE/NOT NECESSARILY TRUE (F) (no working needed, just circle the answer):
 - T An $n \times n$ matrix A is invertible if and only if det $A \neq 0$.
 - T The map $T : \mathbb{P}_2 \to \mathbb{R}^2$ such that $T(\mathbf{p}(t)) = \begin{bmatrix} 0 \\ \mathbf{p}(3) \end{bmatrix}$ is a linear transformation. (Here, \mathbb{P}_2 is the vector space consisting of polynomials of degree at most 2.)
 - T The space \mathbb{P} of all polynomials is infinite dimensional.
 - F The column space of an $m \times n$ matrix is a subspace of \mathbb{R}^n .
 - T Let A be any matrix with n rows. If there is such a matrix C such that $CA = I_n$, then A is invertible.
 - T Any set of n vectors that span \mathbb{R}^n is a basis for \mathbb{R}^n .
 - F Let A be a 3×7 matrix. It is possible that dimNulA = 3.

- 2. [12 points] Consider the matrix $A = \begin{bmatrix} 1 & 0 & 6 \\ 1 & -2 & 8 \\ 0 & 3 & 0 \end{bmatrix}$.
 - (a) Find det A.

det
$$A = 0 - 3 \begin{vmatrix} 1 & 6 \\ 1 & 8 \end{vmatrix} + 0 = -3(8 - 6) = -6$$

(b) Find $det(A^5)$. You do not need to simplify your answer.

$$\det(A^5) = (\det A)^5 = (-6)^5$$

(c) Find A^{-1} .

- (d) Suppose B is a 3×3 matrix such that det B = 5. Based on your answer for part (a), find each of the following.
 - i. the number of pivot positions of A.

	3
ii. $\operatorname{rank}(BA^{-1})$.	
	3
iii. Span Col (A^4) .	
	\mathbb{R}^{3}
iv. dim Nul <i>B</i> .	
	0

- 3. [3 points] Let $V = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} : x \ge 0, y \ge 0 \right\}$ be the set of vectors lying in the first quadrant of the xy-plane. Prove that V is not a vector space. State clearly which axiom does not hold and explain why.
 - V does not satisfy the axiom " $c\mathbf{u}$ is in V" because $-1\begin{bmatrix} x\\ y \end{bmatrix} = \begin{bmatrix} -x\\ -y \end{bmatrix}$ so if $\begin{bmatrix} x\\ y \end{bmatrix}$ is in $V, x \ge 0$ and $y \ge 0$, i.e., $-x \le 0$ and $-y \le 0$, thus $\begin{bmatrix} -x\\ -y \end{bmatrix}$ is not in V.

- 4. [12 points]
 - (a) Using the definition of a subspace (and no other theorems), show that the set W consisting of all vectors of the form $\begin{bmatrix} s+3t\\4t\\0 \end{bmatrix}$ is a subspace of \mathbb{R}^3 .
 - **0** is in W: Let s = 0 and t = 0, then $\begin{bmatrix} 0+3(0)\\4(0)\\0 \end{bmatrix} = \begin{bmatrix} 0\\0\\0 \end{bmatrix}$ is in W.

Let
$$\mathbf{u} = \begin{bmatrix} s_1 + 3t_1 \\ 4t_1 \\ 0 \end{bmatrix}$$
 and $\mathbf{v} = \begin{bmatrix} s_2 + 3t_2 \\ 4t_2 \\ 0 \end{bmatrix}$ be in W . Then
$$\begin{bmatrix} s_1 + 3t_1 \end{bmatrix} \begin{bmatrix} s_2 + 3t_2 \end{bmatrix} \begin{bmatrix} (s_1 + s_2) + 3t_2 \end{bmatrix}$$

$$\mathbf{u} + \mathbf{v} = \begin{bmatrix} s_1 + 3t_1 \\ 4t_1 \\ 0 \end{bmatrix} + \begin{bmatrix} s_2 + 3t_2 \\ 4t_2 \\ 0 \end{bmatrix} = \begin{bmatrix} (s_1 + s_2) + 3(t_1 + t_2) \\ 4(t_1 + t_2) \\ 0 \end{bmatrix}$$

which is also in W.

• W is closed under scalar multiplication:

Let
$$\mathbf{u} = \begin{bmatrix} s+3t \\ 4t \\ 0 \end{bmatrix}$$
 be in W and c be a scalar. Then $c\mathbf{u} = \begin{bmatrix} (cs)+3(ct) \\ 4(ct) \\ 0 \end{bmatrix}$ which is also in W .

(b) Find a basis B for the subspace W.

$$\begin{bmatrix} s+3t\\4t\\0\end{bmatrix} = s \begin{bmatrix} 1\\0\\0\end{bmatrix} + t \begin{bmatrix} 3\\4\\0\end{bmatrix}$$

So $\left\{ \begin{array}{cc} 1 & 3 \\ 0 & 4 \\ 0 & 0 \end{array} \right\}$ is a basis for W. (They clearly span W, and are linearly independent

because neither is a multiple of the other.)

(c) What is dim W?

 $\dim W = 2$

- (d) Geometrically, what does W represent? W is a plane through the origin
- (e) Add an appropriate number of vectors to the set B from part (b) so that the new set is a basis for \mathbb{R}^3 .

$$\left\{ \begin{bmatrix} 1\\0\\0 \end{bmatrix}, \begin{bmatrix} 3\\4\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\1 \end{bmatrix} \right\} \text{ is a basis for } \mathbb{R}^3.$$

Solution. We have the coordinate map

$$V \to \mathbb{R}^{3}$$

$$\mathbf{x} \mapsto [\mathbf{x}]_{\mathcal{B}}$$
One-to-one: Let $\mathbf{u}, \mathbf{v} \in V$ such that $[\mathbf{u}]_{\mathcal{B}} = [\mathbf{v}]_{\mathcal{B}} = \begin{bmatrix} r_{1} \\ r_{2} \\ r_{3} \end{bmatrix}$. Then
$$\mathbf{u} = r_{1}\mathbf{b}_{1} + r_{2}\mathbf{b}_{2} + r_{3}\mathbf{b}_{3}$$

$$\mathbf{v} = r_{1}\mathbf{b}_{1} + r_{2}\mathbf{b}_{2} + r_{3}\mathbf{b}_{3}$$
so
$$\mathbf{u} = \mathbf{v}$$

$$\mathbf{u} = \mathbf{v},$$

and the transformation is one-to-one.

(Alternatively, we may want to show that $[\mathbf{x}]_{\mathcal{B}} = \mathbf{0}$ only if $\mathbf{x} = \mathbf{0}$. Then

$$\mathbf{x} = 0\mathbf{b}_1 + 0\mathbf{b}_2 + 0\mathbf{b}_3 = \mathbf{0},$$

and the map is again one-to-one.)

Onto: Given any $\begin{bmatrix} t_1 \\ t_2 \\ t_3 \end{bmatrix} \in \mathbb{R}^3$, we want to find its preimage under the coordinate map. Let $\mathbf{x} = t_1 \mathbf{b}_1 + t_2 \mathbf{b}_2 + t_3 \mathbf{b}_3$, then $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} t_1 \\ t_2 \\ t_3 \end{bmatrix}$, and the map is onto.

6. [10 points] Consider the matrix
$$A = \begin{bmatrix} 1 & -1 & 1 & 1 & 2 \\ -3 & 4 & -3 & -2 & -4 \\ -2 & 4 & -2 & 0 & 0 \end{bmatrix}$$
.

(a) Find a basis for NulA. What is dim NulA?

Solution.

$$\begin{bmatrix} 1 & -1 & 1 & 1 & 2 \\ -3 & 4 & -3 & -2 & -4 \\ -2 & 4 & -2 & 0 & 0 \end{bmatrix} \xrightarrow{R_2 \leftarrow R_2 + 3R_1} \begin{bmatrix} 1 & -1 & 1 & 1 & 2 \\ 0 & 1 & 0 & 1 & 2 \\ -2 & 4 & -2 & 0 & 0 \end{bmatrix} \xrightarrow{R_3 \leftarrow R_3 + 2R_1} \begin{bmatrix} 1 & -1 & 1 & 1 & 2 \\ 0 & 1 & 0 & 1 & 2 \\ 0 & 2 & 0 & 2 & 4 \end{bmatrix}$$

$$R_3 \leftarrow R_3 - 2R_2 \begin{bmatrix} 1 & -1 & 1 & 1 & 2 \\ 0 & 1 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1 \leftarrow R_1 + R_2} \begin{bmatrix} 1 & 0 & 1 & 2 & 4 \\ 0 & 1 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$
We get

g

$$x_1 = -x_3 - 2x_4 - 4x_5$$
$$x_2 = -x_4 - 2x_5$$

 x_3, x_4, x_5 free.

Since there are 3 free variables, dim NulA = 3. Furthermore

$$\operatorname{Nul} A = x_3 \begin{bmatrix} -1\\0\\1\\0\\0 \end{bmatrix} + x_4 \begin{bmatrix} -2\\-1\\0\\1\\0 \end{bmatrix} + x_5 \begin{bmatrix} -4\\-2\\0\\0\\1 \end{bmatrix}$$

and a basis is

$$\left\{ \begin{bmatrix} -1\\0\\1\\1\\0\\0 \end{bmatrix}, \begin{bmatrix} -2\\-1\\-2\\0\\0\\1\\0 \end{bmatrix}, \begin{bmatrix} -4\\-2\\0\\0\\1\\0 \end{bmatrix} \right\}.$$

(b) Find a basis for ColA. What is dim ColA?

Solution. There are 2 basic variables, so dim ColA = 2. Furthermore, a basis corresponds to the pivot columns in A and we have a basis

$$\left\{ \begin{bmatrix} 1\\-3\\-2 \end{bmatrix}, \begin{bmatrix} -1\\4\\4 \end{bmatrix} \right\}.$$

(c) Find a basis for RowA.

Solution. We have dim ColA = dim RowA = 2. Furthermore, a basis corresponds to the pivot rows in the echelon form of A and we have a basis

_ _

$$\left\{ \begin{bmatrix} 1\\0\\1\\1\\2\\4 \end{bmatrix}, \begin{bmatrix} 0\\1\\0\\1\\2\\4 \end{bmatrix} \right\}.$$

7. [5 points] Let
$$\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 4 \\ -3 \end{bmatrix} \right\}$$
 and $\mathcal{C} = \left\{ \begin{bmatrix} 2 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$ be bases for \mathbb{R}^2 .

Find the change of basis matrices $\underset{\mathcal{C} \leftarrow \mathcal{B}}{P}$ and $\underset{\mathcal{B} \leftarrow \mathcal{C}}{P}$. Solution. We have $\underset{\mathcal{C} \leftarrow \mathcal{B}}{P} = [[\mathbf{b}_1]_{\mathcal{C}} \ [\mathbf{b}_2]_{\mathcal{C}}]$, so we row-reduce concomitantly

 $\begin{bmatrix} \mathbf{c}_1 & \mathbf{c}_2 \mid \mathbf{b}_1 & \mathbf{b}_2 \end{bmatrix} \Longrightarrow \begin{bmatrix} I_2 \mid P_{\mathcal{C} \leftarrow \mathcal{B}} \end{bmatrix}$

$$\begin{bmatrix} 2 & 1 & 1 & 4 \\ -1 & 0 & -1 & -3 \end{bmatrix} \xrightarrow{R_1 \leftarrow R_1 + 2R_2} \begin{bmatrix} 0 & 1 & -1 & -2 \\ -1 & 0 & -1 & -3 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow -R_2} \begin{bmatrix} 1 & 0 & 1 & 3 \\ 0 & 1 & -1 & -2 \end{bmatrix}$$
$$P_{\mathcal{C} \leftarrow \mathcal{B}} = \begin{bmatrix} 1 & 3 \\ -1 & -2 \end{bmatrix}.$$

Since

 \mathbf{SO}

$$\underset{\mathcal{B}\leftarrow\mathcal{C}}{P}=(\underset{\mathcal{C}\leftarrow\mathcal{B}}{P})^{-1}$$

we get

$$P_{\mathcal{B}\leftarrow\mathcal{C}} = \frac{1}{-2 - (-3)} \begin{bmatrix} -2 & -3\\ 1 & 1 \end{bmatrix} = \begin{bmatrix} -2 & -3\\ 1 & 1 \end{bmatrix}$$

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