

M116 lec 2

- poweriter.m
- learn names:
- steer paper choices

① 3/27/14

Today: iter. method for EVP, conditioning, stability

Last time: direct vs iterative complexity

convergence rate of error to zero vs  $k$  (#-iters, effort):

types:  $k^{-p}$  (ask) algebraic order  $p$   
 $r^k$  rate  $r \in (0,1)$  (ask) geometric / exp. / linear.

EVP: Power iteration for dominant eigvec  $v_1$

recall Power iteration:  $x^{(0)}$  random,  $x^{(k+1)} = Ax^{(k)}$  then normalize each step.

Showed  $x^{(k)} \rightarrow v_1$  w/ exp. rate  $r = |\frac{\lambda_2}{\lambda_1}|$

(code) poweriter.m, can be terribly slow. (rerun w/ random  $A$ 's)

how incr. rate? get other evecs  $v_m$ ?

$$A = V\Lambda V^T$$

let  $\mu \in \mathbb{R}$ ,

it is a spectral decomp.

means  $(A - \mu I)^{-1}$  has a huge eignal if  $\mu$  near a  $\lambda_j$ .

$$(A - \mu I)^{-1} = V \text{diag}\{(\lambda_j - \mu)^{-1}\} V^T$$

← why?

gives  $I$  when pre- or post-mult. by  $A - \mu I = V(\Lambda - \mu I)V^T$   
 since  $V^T V = V V^T = I$ .

"Inverse iteration"

let  $\mu$  be an estimate for  $\lambda_m$ ,  $x^{(0)}$  rand.  $\in \mathbb{R}^n$

for  $k=1, 2, \dots$

$$\text{solve } (A - \mu I)w = x^{(k-1)}$$

for  $w \in \mathbb{R}^n$ .

$$x^{(k)} = w / \|w\|$$

end.

• apply power iteration to  $(A - \mu I)^{-1}$

• convergence: let  $\lambda_m$  be closest to  $\mu$ ,  $\lambda_s$  2<sup>nd</sup>-closest, then reuse them on power iter,

$$\text{Thm: } \|x^{(k)} - (\pm)v_m\| = O\left(\left|\frac{\lambda_m - \mu}{\lambda_s - \mu}\right|^k\right)$$

code: poweriter.m pt II, fast.

\* Estimating  $\lambda_m$  from  $x$ , an estimate for  $v_m$ ?

(ask)

Rayleigh quotient  $R(x) := \frac{x^T A x}{x^T x}$

Lord Rayleigh, 1880.

why good?

$$x = \sum \alpha_j v_j$$

$$x^T x = \sum_j \alpha_i \alpha_j \underbrace{v_i^T v_j}_{\delta_{ij}} = \sum \alpha_j^2$$

$$x^T A x = \sum_j \alpha_i \alpha_j \underbrace{v_i^T A v_j}_{\lambda_j \delta_{ij}} = \sum \lambda_j \alpha_j^2$$

$$\text{so } R(x) = \frac{\sum \lambda_j \alpha_j^2}{\sum \alpha_j^2} \approx \lambda_m \text{ if } \begin{cases} \alpha_m \text{ large} \\ \alpha_j \text{ small, } j \neq m \end{cases}$$

ask which decays faster?  
 $r^k = o(k^{-p})$   
 little-oh meaning?  
 $f(k) = o(g(k))$   
 if  $\lim_{k \rightarrow \infty} \frac{f(k)}{g(k)} = 0$   
 HW: pf.

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Thm: say  $\|x - v_m\| = \epsilon$  then  $R(x) - \lambda_m = O(\epsilon^2)$  as  $\epsilon \rightarrow 0$ .

pf 2:  $R(x)$  stationary at  $x = v_m$  i.e.  $\nabla R = \vec{0}$  (Necessary), and  $R(v_m) = \lambda_m$

Since  $R(x)$  smooth for  $x \neq 0$ , holds by calculus.

pf 1:  $\|\sum \alpha_j v_j - v_m\|^2 = \epsilon^2$

since o.n.b.  $(\alpha_m - 1)^2 + \sum_{j \neq m} \alpha_j^2 = \dots$  so  $|\alpha_m - 1| \leq \epsilon$

$R$  (scale-invariant):

rescale  $x$  so  $\alpha_m = 1$ , then  $\sum_{j \neq m} \alpha_j^2 \leq \frac{\epsilon^2}{(1-\epsilon)^2} = \delta$  &  $\sum_{j \neq m} \alpha_j^2 \leq \epsilon^2$

$$R(x) = \frac{\lambda_m + \sum_{j \neq m} \lambda_j \alpha_j^2}{1 + \sum_{j \neq m} \alpha_j^2} \leq \frac{\lambda_m + \max_j |\lambda_j| \delta}{1 - \delta} \leftarrow \text{worst case}$$

$$= \lambda_m (1 + O(\delta)) \quad \text{using eg. } \frac{1}{1-\delta} = 1 + O(\delta) \text{ etc.}$$

sim for lower bound.

asympt rules

Show  $\hat{\lambda} = R(x^{(k)})$  in inverse iter code - how many more digits  $\hat{\lambda}^{(k)}$  converge than  $x^{(k)}$ ? twice.

Any ideas how to improve inverse iter? use  $N = R(x^{(k-1)}) = \hat{\lambda}^{(k-1)}$  best avail. eigen.

"Rayl. Quot Iter"



Thm:  $\forall x^{(0)}$  except set meas. zero, conv. obeys  $\epsilon_{k+1} = O(\epsilon_k^3)$

where  $\epsilon_k := \|x^{(k)} - \pm v_m\|_2$

or  $:= |\lambda^{(k)} - \lambda_m|$

w/ const in  $O(\cdot)$  uniform for  $k$  suff. large.

each iter triples # correct digits!

Cubic convergence: means  $\epsilon_k \leq C \epsilon_{k-1}^3 \leq C' \epsilon_{k-2}^9 \dots$

ask: faster than exp.?

ie  $\epsilon_k = O(r^{3^k})$   $r \in (0,1)$

$\exists$  alg. that are 'quadratic' conv.  $\epsilon_{k+1} = O(\epsilon_k^2)$  eg. Newton's method finding roots.

pf sketch: say  $\|x^{(k)} - \pm v_m\| = \epsilon$

then  $|\lambda^{(k)} - \lambda_m| = O(\epsilon^2)$

so  $|\frac{\lambda - N}{\lambda_2 - N}| = O(\epsilon^2) \leftarrow$  so 1 step inv. iter mult. error by this

$\Rightarrow \|x^{(k+1)} - \pm v_m\| = \epsilon O(\epsilon^2)$

$\hat{\lambda}^{(k)}, x^{(k)}$  conv. at same rate.

code show pt III

note:  $O(n^3)$  per step but only  $< 5$  needed.

BREAK

Damian v. excited by exploring which  $\lambda_j$   $N$  settles on.

Much better:  $JQ(n^3)$  vs  $\lambda_5$ .  
eg. QR iteration Francis paper, builds on this.

Condition # of problem.

(as M126 W12, NLA §12)

numerical problem is map  $f: X \rightarrow Y$   
input space  $X$  space of answers  $Y$

eg  $f(x) = \tan x$  eval. some func.

eg  $f(\{a_0, \dots, a_p\}) = \{z_1, \dots, z_p\}$   
 poly coeffs. roots of poly.

$f$  'well-cond.' if infinitesimal pert.  $\delta x$  in  $x$  causes 'small' pert.  $\delta f := f(x+\delta x) - f(x)$

Defn Abs. cond. #  $\kappa = \kappa(x) := \lim_{\delta \rightarrow 0} \sup_{\|\delta x\| \leq \delta} \frac{\|\delta f\|}{\|\delta x\|} = \text{abbrev} \sup_{\delta x} \frac{\|\delta f\|}{\|\delta x\|}$

"norm of Frechet derivative" "Lipschitz const. at point  $x$ ."  $\uparrow \uparrow \uparrow$  e.g. 2-norms.

if  $x \in \mathbb{C}^n$ ,  $f(x) \in \mathbb{C}^m$  vectors,  $\frac{\partial f_i}{\partial x_j} = J_{ij}(x)$  matrix  $J \in \mathbb{C}^{m \times n}$ . Jacobian.

If  $f$  smooth then  $\delta f \approx J \delta x$  as  $\|\delta x\| \rightarrow 0$ . (locally linear)

Mult. by given matrix  $J$ , what is largest factor by which length of vector can grow?

"max growth factor" =  $\|J\|_2$  or  $\|J\|$  2-norm of matrix.  $= \sup_{0 \neq x \in \mathbb{C}^n} \frac{\|Jx\|}{\|x\|} = \sup_{\|x\|=1} \|Jx\|$

Properties:   
 - say  $A = \text{diag}\{a_1, \dots, a_n\} \in \mathbb{R}^{n \times n}$  what is  $\|A\|$ ?  $= \max |a_j|$  (was tricky)   
 - say  $A = uv^T$   $u \in \mathbb{R}^m, v \in \mathbb{R}^n$    
 $\in \mathbb{R}^{m \times n}$ , a rank-1 matrix.  $\|Ax\| = |v^T x| \|u\| \leq \|v\| \|x\|$  by what? C-S.   
 so  $\|A\| = \|u\| \|v\|$    
 "smallest C st.  $\|Jx\| \leq C \|x\| \forall x$ "

$\|AB\| \leq \|A\| \|B\|$  submultiplicator. since  $\|ABx\| \leq \|A\| \|Bx\| \leq \|A\| \|B\| \|x\|$    
 square  $A$  can have all  $\lambda_j = 1$  but huge  $\|A\|$ , give example.   
 is this C-S? No! Defn of norm.

So for vector func  $f: \mathbb{C}^m \rightarrow \mathbb{C}^n$ , abs cond #  $\hat{\kappa}(x) = \|J(x)\|_2$    
 got here!   
 more useful:

Relative cond #  $\kappa := \sup_{\delta x} \frac{\|\delta f\| / \|f\|}{\|\delta x\| / \|x\|} = \frac{\|J(x)\|}{\|f\| / \|x\|}$

rel. change in input & output: important since computer introduces relative errors.

say  $\kappa \leq 10^3$  well-cond. otherwise ill-cond.  $\gg 10^3$ .

$\kappa$  is property of problem not alg. used to solve it.