

Nystrom beautifully efficient, & inherits the convergence of the quadr. scheme applied to $k(s, \cdot)u(\cdot)$, for certain well-behaved ops K , called 'compact'.

If I drop \int in (6), can apply to 1^{st} -kind (HW4), solving for $u_j^{(n)}$, but there is no interpolation formula (N).
To solve, need some theory.

Compact operators: may have ∞ -dim range but behave 'like' finite-dim. ops. (length)

consider funcs f in $\text{eg } C[a, b]$ as points in topological space, $X = C[a, b]$, w/ metric (norm) $\|f\|$,
eg. $\|f\|_{\infty} = \sup_{s \in [a, b]} |f(s)|$

- seq $(f_n)_{n=1,2,\dots}$ bounded if $\|f_n\| \leq C (< \infty) \quad \forall n=1,2,\dots$ note: seq. goes on forever (long time)
 - seq. (f_n) converges to $f \in X$ if $\forall \epsilon > 0$ no matter how small, $\exists N$ st. $\|f_n - f\| < \epsilon \quad \forall n \geq N$
- Say f_n were points in finite-dim space, eg \mathbb{R}^m , w/d apply Bolzano-Weierstrass.

Thm: in finite-dim normed space, every. bnded seq. contains a convergent. subseq. (also goes on forever)
Eg. try it in \mathbb{R} : the only way to avoid having some limit pt is to escape to $\pm \infty$.
B-W proof uses this fact successively on each coord $1, 2, \dots, m$ in \mathbb{R}^m .

However ∞ -dim space such as $C[a, b]$, $L^2[a, b]$, etc. are fundamentally different.

Eg. seq. $\{\sin(nX)\}_{n=1}^{\infty}$ is bounded in $C[0, 2\pi)$ or $L^2[0, 2\pi)$, but has no convergent subseq.
Eg. any other. o.n.b.

E.g. l_2 : space of sequences $\{a_1, a_2, \dots\}$ with $\sum_{j=1}^{\infty} |a_j|^2 < \infty$ has o.n.b.
 $\begin{cases} \{1, 0, 0, \dots\} \\ \{0, 1, 0, \dots\} \\ \{0, 0, 1, \dots\} \\ \dots \end{cases}$ etc.

Convergence: seq. (x_n) in normed space X converges to x if $\forall \epsilon > 0 \exists N$ st. $\|x_n - x\| < \epsilon \quad \forall n \geq N$

Defn: [Lin. op. $K: X \rightarrow Y$ between normed lin. spaces X & Y is compact if given any bounded seq. (x_n) in X , the seq. (Kx_n) contains a convergent subseq. (I.e. K maps bounded sets \rightarrow 'precompact sets' (which must contain convergent subseqs).)
as if 'finite-dim.'

Eg. if K has finite-dim range, B-W $\Rightarrow (Kx_n)$ has conv. subseq., so K cpt.
 eg. $(K\alpha)(s) = \int_a^b \sum_{i=1}^N \alpha_i(s) \beta_i(t) u(t) dt$
 finite sum of rank-1 kernels.

Conversely $K = Id$ with $X=Y$ ∞ -dim spaces maps $(x_n) \rightarrow (x_n)$ so need not contain conv. subseq.,
 ie Id is compact iff Y finite-dim. not cpt.

Thm: Compact ops are bounded. { pf. suppose not, then \exists seq. (x_n) with $\|x_n\| = 1 \quad \forall n=1,2,\dots$
 st. $\|Kx_n\| > n$
 But this cannot contain convergent subseq. $\Rightarrow K$ not compact.

But, bounded \neq compact, viz. Id .

K Compact := finite-dim, or ∞ -dim in a way that components made arbitrarily small as $\text{dim} \rightarrow \infty$.

still need final 1/2 hr on Ascoli Thm.

① Thurs. 10/23/08

- Coding tips.
- $\|K\|_2$ upper bound via Hilbert-Schmidt, then $k(s,t) = \frac{1}{|s-t|^\alpha}$ is H-S for $0 < \alpha < 1/2$
- Compactness. (③ 10/21)

Why compactness useful?

1) Thm (Fredholm Alternative). Let $K: X \rightarrow X$ be compact on normed lin. space X .
 Then either i) for each $f \in X$, $(I - K)u = f$ has unique soln. $u \in X$
 or ii) homog. eqn. $(I - K)u = 0$ has nontrivial soln. \leftarrow the alternative.
 If case i) holds, $(I - K)^{-1}$, whose existence is asserted there, is bounded.

• I.e., $(I - K)$ surjective iff injective. Note: eg. left-shift op. on l_2 has nontrivial nullsp. but also i) holds, in contrast.
 Cf. invertible matrix thm: $A\vec{x} = \vec{b}$ soln exists, unique, iff $A\vec{x} = \vec{0}$ has only triv soln.
 Means $(I - K)$ behaves like finite-dim square matrix (either invertible or not).

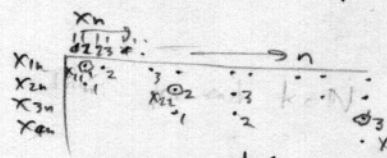
Useful: if $\exists \lambda \in \mathbb{C} \setminus \{1\}$ s.t. $(I - \lambda K)u = 0$ has only triv soln, i.e. λ is not an eigenval of K , then 2nd kind IE (soln always exists, unique)

2) we can prove convergence rate of Nyström method for compact K is $\|u^{(n)} - u\|_\infty \leq C \|Ku - K_n u\|_\infty$

Defn: (x_n) Cauchy convergent if $\forall \epsilon > 0, \exists N$ s.t. $\|x_n - x_m\| \leq \epsilon$ for all $n, m > N$.
 • $(x_n) \rightarrow x \Rightarrow$ Cauchy.
 • if Cauchy seq. always convergent to an $x \in X$, X is complete (called Banach space), eg $C[a,b]$ in $\|\cdot\|_\infty$, $L^2[a,b]$, etc. (not $C[a,b]$ in $\|\cdot\|_2$)

Tests for compactness:

1) Thm: Let K_1, K_2, \dots be seq. of compact ops $X \rightarrow Y$ (Y complete) s.t. $\lim_{n \rightarrow \infty} \|K_n - K\| = 0$, then K compact.
 Rmk: eg. cpt if seq. of finite-dim ops which conv. in norm to it, eg. $U_j \rightarrow \frac{1}{j} U_j$ in l_2 : K_n is $U_j \rightarrow \frac{1}{j} U_j, j \leq n$; $U_j \rightarrow 0, j > n$ so $K - K_n$
 Pf: let (x_n) bnded seq. \exists subseq (x_{n_k}) s.t. (Kx_{n_k}) convergent.
 \exists subseq of this, $(x_{n_{k_l}})$ s.t. $(Kx_{n_{k_l}})$ conv. ... etc.



If can show $(Kx_{n_{k_l}})$ conv. too, we've proved K cpt since for any (x_n) we found Kx_{n_k} has conv. subseq.

Let $\epsilon > 0$: $\exists k$ s.t. $\|K - K_k\| \leq \frac{\epsilon}{3M}$ where $M = \sup \|x_n\|$
 Let k_l be s.t. $\|K_k x_{n_{k_l}} - K_k x_{n_{k_l}}\| \leq \epsilon/3$ ($\forall n, m > k_l$ since $K_k x_{n_{k_l}}$ conv. & its Cauchy)
 then $\|Kx_{n_{k_l}} - Kx_{n_{k_l}}\| \leq \underbrace{\|Kx_{n_{k_l}} - K_k x_{n_{k_l}}\|}_{\leq \epsilon/3} + \underbrace{\|K_k x_{n_{k_l}} - K_k x_{n_{k_l}}\|}_{\leq \epsilon/3} + \underbrace{\|K_k x_{n_{k_l}} - Kx_{n_{k_l}}\|}_{\leq \epsilon/3} \leq \epsilon$
 so $(Kx_{n_{k_l}})$ Cauchy \implies conv. to element in Y by completeness.

Ash what looked at each other's work? Who's looked at debriefings? 10/23. (1)

show matlab examples?

Coding tips:

(15mins)

if have param. such as max n (n=1...20), set it once at start of code to have all ~~ref~~ reference this.

switches in code to avoid duplication (don't make many nearly-identical codes; more errors, harder to maintain, read).

finishes at start.

use handles: f=@(n)...
Eval. later but never need to type
quadr. schemes.

modular: $\begin{bmatrix} x & w \end{bmatrix} = \text{gauss}(n)$
nodes | wei
↑
order: n

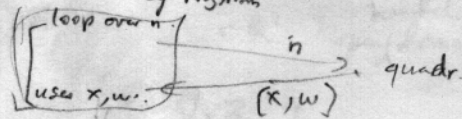
defines a uniform interface.

have other quadr. schemes return in same way:

$\begin{bmatrix} x & w \end{bmatrix} = \text{comptrap}(n)$

$\text{equal}(\text{newtoncotes}(n))$

main code eg Nystrom



(Finish opt)

Lec. 10

10/28/08

(2)

Cpt ops K: a) Fredholm Alt: unique solvability of $(I-K)u=f$ if $\text{Nul}(I-K) = \{0\}$, ...
b) Nystrom conv. at same rate as quadr. scheme.

what means for spectrum of K?
1 is not eigenvalue
($\lambda=1: Ku=u$ for some u)

2) Fredholm K w/ $K \in C[a,b]^2$ is compact on $C[a,b]$.

Pf: i) show that K maps bounded seq (u) to 'equicontinuous' bnded seq.

eg. $u_n(t) = x^n$ - not equicontinuous on $[0,1]$ - why not?
C (u_n) set of fncs: $\forall \epsilon > 0 \exists \delta$ st.

ii) then by Arzela-Ascoli thm such sets are compact. (seq. contain conv. subseq.) ... proof by diagonalization & $\epsilon/3$ tricks.

Shgori only:

$|(Ku)(s)| \leq M|b-a| \max_{s,t} |k(s,t)|$

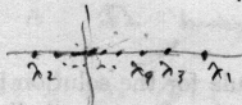
where $M := \sup_{n \in \mathbb{N}} \|u_n\|$.

K cont on square: $\forall \epsilon > 0 \exists \delta$ st. $|k(s,t) - k(r,t)| \leq \frac{\epsilon}{M(b-a)}$ whenever $|s-r| < \delta$

then $|(Ku)(s) - (Ku)(r)| \leq | \int_a^b (k(s,t) - k(r,t)) u_n(t) dt | \leq |b-a| \max_{|s-r| < \delta} |k(s,t) - k(r,t)| \|u_n\| \leq \epsilon$

→ seq (K_n) equicontinuous.

Spectral thm for compact ops: K compact: has spectrum of discrete, finite-multiplicity eigenvalues, with 0 the only limit pt.



no nasty 'continuous spectrum, etc.'

since $\lambda_n \rightarrow 0$. think of map to ellipsoid w/ shrinking semi-axes.

($\lambda_n = \sigma_n$ SVD, if Hermitian, self-adjoint)



finish cpt ops.

Tools for Laplace's Eqn.

$$\frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}$$

$$\Delta u = 0 \Leftrightarrow u \text{ a harmonic func.}$$

diffusion steady-state heat flow, electrostatics

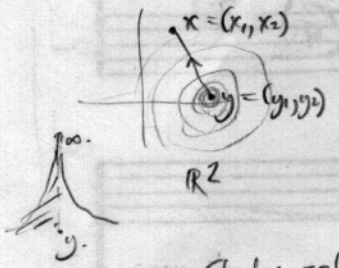
plan: finish cpt. (20 mins)

Fund soln. in \mathbb{R}^2 , Δ kills GT1, 2.

1) Fundamental soln.

$$\Phi(x,y) = -\frac{1}{2\pi} \ln|x-y| \quad x,y \in \mathbb{R}^2$$

also 'free-space Green's func': will give integral kernel for solution op.



Fact: for each $y \in \mathbb{R}^2$, $\Phi(\cdot, y)$ is harmonic in $\mathbb{R}^2 \setminus \{y\}$

$$\text{i.e. } \Delta_x \Phi(x,y) = 0 \quad \forall x \neq y$$

- ? prove GRF -
- note as layer pots, define LPS, as int. op.
- formula for $\frac{\partial \Phi}{\partial n_j}(x,y)$.
- change of variables for $y(t)$ parametric curve.

Check: set $y=0$ without loss of generality, then $\frac{\partial}{\partial x_1} \ln|x| = \frac{1}{2} \frac{\partial}{\partial x_1} \ln(x_1^2 + x_2^2)$

$$= \frac{1}{2(x_1^2 + x_2^2)} \cdot 2x_1 = \frac{x_1}{|x|^2} \quad x \neq 0 \text{ etc.}$$

since $x \leftrightarrow y$ symm, $\Delta_y \Phi(x,y) = 0 \quad \forall y \neq x$.

2) Divergence Thm:

$\Omega \subset \mathbb{R}^2$ bounded open domain w/ boundary $\partial\Omega$, $\vec{a} = \begin{pmatrix} a_1(x) \\ a_2(x) \end{pmatrix}$ vector field cont. on $\partial\Omega$ & C^1 cont inside,

$$\int_{\Omega} \nabla \cdot \vec{a} \, dx = \int_{\partial\Omega} \hat{n} \cdot \vec{a} \, ds$$

area arc length on $\partial\Omega$

div $\vec{a} := \frac{\partial a_1}{\partial x_1} + \frac{\partial a_2}{\partial x_2}$ outward flux through $\partial\Omega$

\hat{n} outward unit normal.

Ω may have corners.
everything comes from these two.

$\int \hat{n}_j \cdot \vec{a}(y) \, ds_j$ explicitly.

Green's Thms: u, v be sufficiently smooth funcs defined in $\bar{\Omega}$ & closure $\Omega + \partial\Omega$

$$\int_{\Omega} (u \Delta v + \nabla u \cdot \nabla v) \, dx = \int_{\partial\Omega} u \frac{\partial v}{\partial n} \, ds \quad (GT1)$$

$:= V_n := \hat{n} \cdot \nabla v$

$$\int_{\Omega} u \Delta v - v \Delta u \, dx = \int_{\partial\Omega} u v_n - v u_n \, ds \quad (GT2)$$

pf: do as WS?
 $\nabla \cdot (u \nabla v) = \text{prod rule } \nabla u \cdot \nabla v + \nabla u \cdot \nabla v$
 apply Div. Thm to $\vec{a} = u \nabla v$ to get GT1.
 GT2 by subtracting GT1 with $u \leftrightarrow v$ from itself.

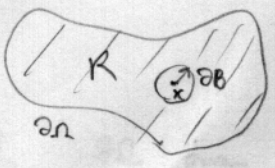
sufficient smoothness is Ω having C^1 smooth bdry, $u, v \in C^2(\bar{\Omega})$, however can be loosened to Ω w/ corners.

Corollary: setting $u=1$ in GT1; If v harmonic in Ω then $\int_{\partial\Omega} v_n \, ds = 0$ (zero-flux)

Green's Representation Formula: Let u be harmonic in Ω , then for each $x \in \Omega$,

$$u(x) = \int_{\partial\Omega} u_n(y) \Phi(x,y) - u(y) \frac{\partial\Phi}{\partial n_y}(x,y) \cdot ds_y$$
 interior values from
 i.e. integral kernels acting on bdy func. u, u_n .

Pf: $\partial B(x;r)$ = circle rad. r about x with inward
 closed ball
 in $R := \Omega \setminus \overline{B(x;r)}$ $\Phi(x,y)$ harmonic as func. of y .



GTZ \forall in R for $u, v = \Phi(x, \cdot)$:

$$\int_R u \Delta \Phi(x,y) - \Phi(x,y) \Delta u \, dx = \int_{\partial R} u(y) \frac{\partial\Phi(x,y)}{\partial n_y} - \Phi(x,y) \frac{\partial u(y)}{\partial n} \, ds_y$$

$\partial R = \partial\Omega + \partial B$
 inward-pointing \hat{n} .

$$\begin{aligned} \text{so } \int_{\partial\Omega} \Phi(x,y) u_n(y) - \frac{\partial\Phi}{\partial n_y}(x,y) u(y) \, ds_y &= \int_{\partial B(x;r)} \frac{\partial\Phi(x,y)}{\partial n_y} u(y) - \Phi(x,y) u_n(y) \, ds_y \\ &= \frac{1}{2\pi r} \int_{\partial B} u(y) \, ds_y + \frac{1}{2\pi} \ln r \int_{\partial B} u_n(y) \, ds_y \\ &= 2\pi r \cdot u(y) \text{ for some } y \in \partial B \text{ by MVT.} \end{aligned}$$

by zero flux

Finally take $\lim_{r \rightarrow 0}$, get $\lim_{r \rightarrow 0} u(y)|_{y \in \partial B} = u(x)$.

Cor: since Φ & $\frac{\partial\Phi}{\partial n_y}$ analytic func. of 2^{nd} variable, u analytic in Ω regardless how nasty the bdy data u, u_n is.

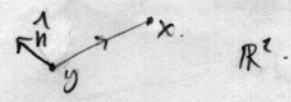
Given a func σ on $\partial\Omega$,
 Define single-layer integral of u $(S\sigma)(x) := \int_{\partial\Omega} \Phi(x,y) \sigma(y) \, ds_y$
 double- $(D\tau)(x) := \int_{\partial\Omega} \frac{\partial\Phi(x,y)}{\partial n_y} \tau(y) \, ds_y$

then GRF says $u = S\sigma + D\tau$ if choose $\sigma = u_n|_{\partial\Omega}$
 $\tau = -u|_{\partial\Omega}$

Other consequences of GRF: let u be harmonic,
 Choose $\Omega = B(x;r)$ then $u(x) = \ln r \int_{\partial\Omega} u_n(y) \, ds_y - \frac{1}{2\pi r} \int u(y) \, ds_y$
zero flux value at center = mean value of u over $\partial B(x;r)$

(2) Maximum principle)

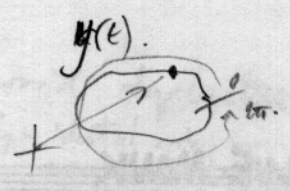
1) Computation: \mathbb{R}^2



given x, y, \hat{n}_y unit vec. $\frac{\partial \Phi(x, y)}{\partial n_y} = -\frac{1}{2\pi} \hat{n} \cdot \nabla_y \ln |x-y| \frac{(x-y)}{|x-y|^2}$

2) $\partial\Omega$ param by $y(t), t \in (0, 2\pi)$:

for some bdy func g



$\int_{\partial\Omega} g(y) ds_y = \int_0^{2\pi} g(y(t)) \underbrace{|y'(t)|}_{\text{speed}} dt$